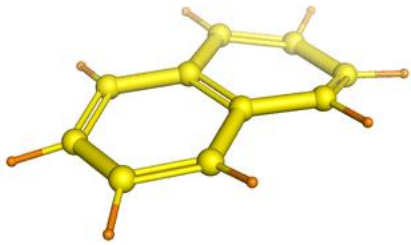


Energy-Motivated Equivariant Pretraining for 3D Molecular Graphs

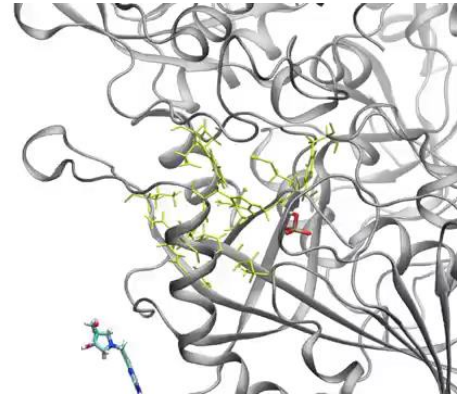
Rui Jiao, Jiaqi Han, Wenbing Huang, Yu Rong, Yang Liu
AAAI 2023

Motivation

- Learning informative molecular representation is fundamental for various downstream applications.



MD Simulation



Ligand Binding

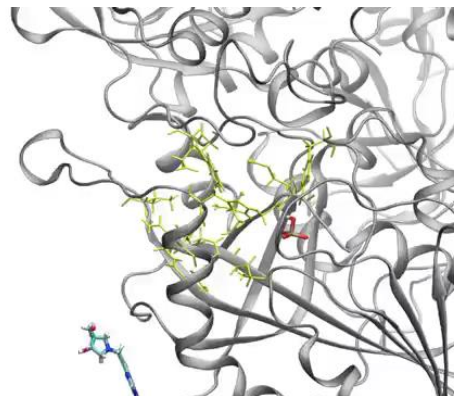
- Equivariant Graph networks (EGNs) are capable to model geometric graphs.
 - SchNet, EGNN, PaiNN, TorchMD-Net, e.t.c.
- Community has provided large-scale molecule datasets with rich 3D conformations.
 - GEOM, Molecule3D, PCQM4Mv2, e.t.c.
- Many self-supervised works have shown superiority in 2D graph learning

Motivation

- Learning informative molecular representation is fundamental for various downstream applications.



MD Simulation



Ligand Binding

3D tasks

- Equivariant Graph networks (EGNs) are capable to model geometric graphs.
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- Community has provided large-scale molecule datasets with rich 3D conformations.
 - GEOM, Molecule3D, PCQM4Mv2, e.t.c.
- Many self-supervised works have shown superiority in 2D graph learning.
- How about **3D pretraining**?

3D models

3D datasets

2D pretraining

Related Works

- Equivariant Graph Neural Networks

- Take EGNN as an example
- E(3) Symmetry

Invariance $\varphi(g \cdot \mathbf{X}, H) = \varphi(\mathbf{X}, H)$

Equivariance $\varphi(g \cdot \mathbf{X}, H) = g \cdot \varphi(\mathbf{X}, H)$

- EGNN Message Passing & Aggregation

$$m_{ij} = \varphi_m(h_i, h_j, \|\mathbf{x}_i - \mathbf{x}_j\|^2, e_{ij}),$$

$$\mathbf{x}'_i = \mathbf{x}_i + \sum_{j \neq i} (\mathbf{x}_i - \mathbf{x}_j) \varphi_x(m_{ij}),$$

$$h'_i = \varphi_h(h_i, \sum_{j \in \mathcal{N}(i)} m_{ij}),$$

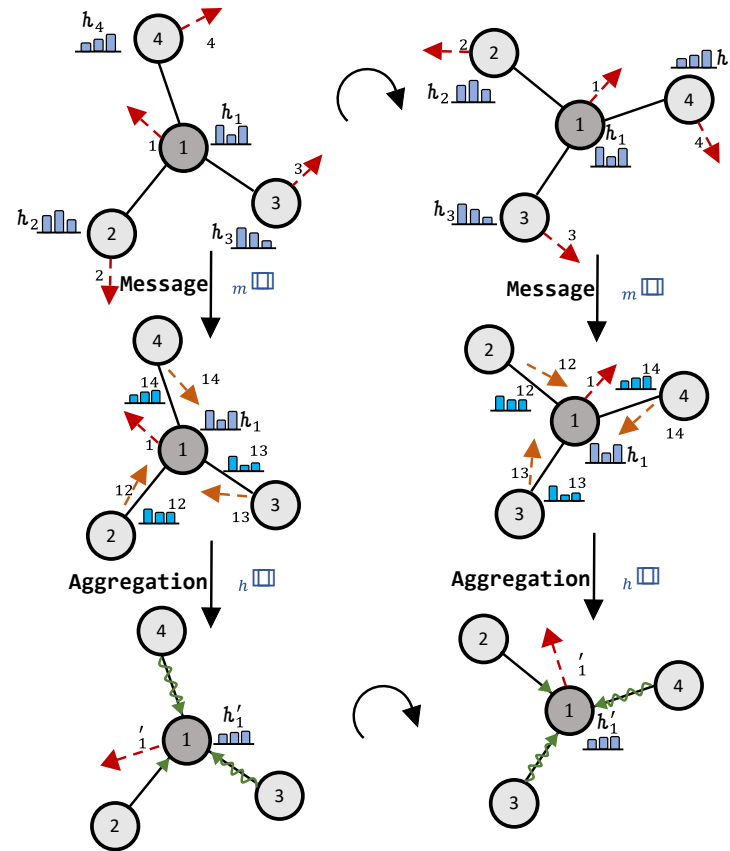


Image taken from Han et. al., 2022

Related Works

- Self-supervised Molecular Pretraining
- 2D Pretraining
 - Contrastive : Maximize MI between different views
 - InfoGraph, GraphCL, JOAO, e.t.c.
 - Generative : Reconstruct the graph components from different levels
 - AttrMask, EdgePred, GPT-GNN, e.t.c.
 - Predictive : Predict domain-specific labels created from the input graphs
 - GROVER, e.t.c.

- 2D + 3D Pretraining
 - GraphMVP
 - 3D Infomax

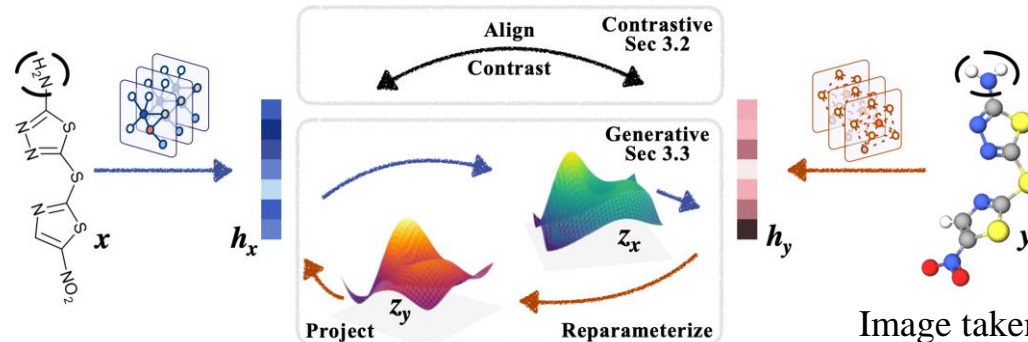


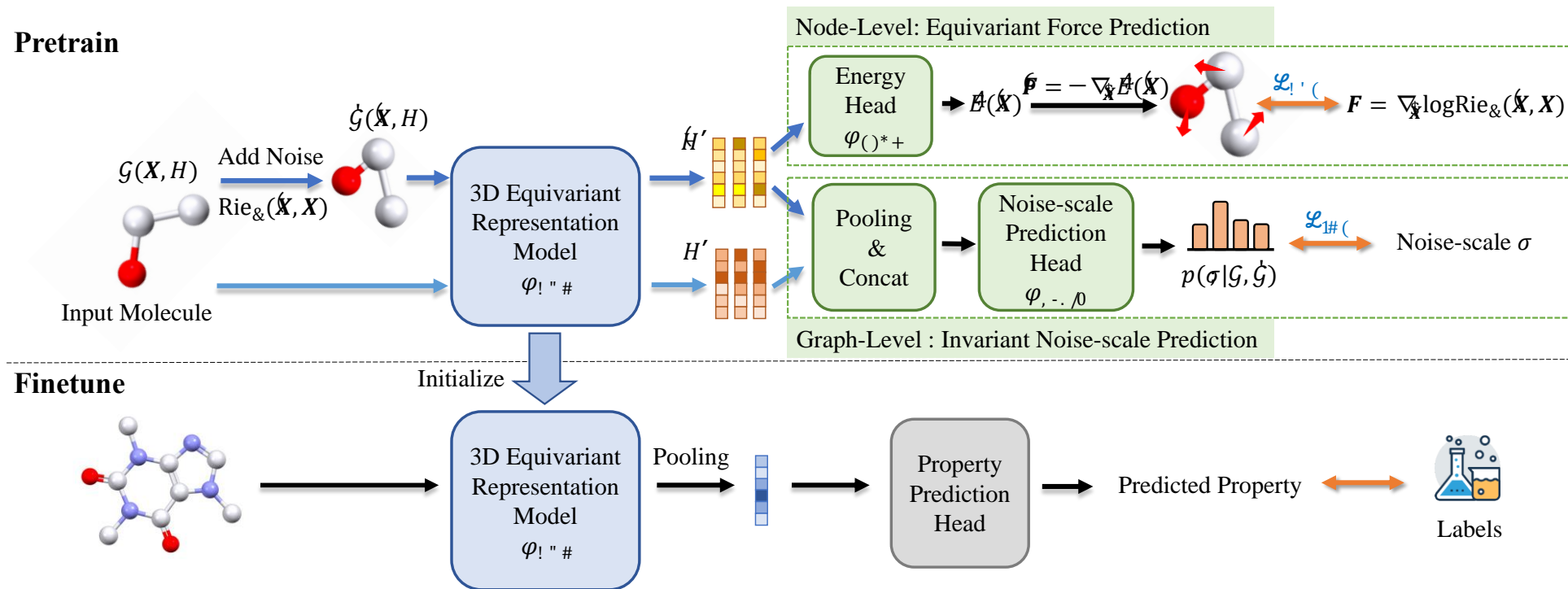
Image taken from Liu et. al., 2022

- Does 2D pretraining methods align well with 3D models?
- Can we design 3D-aware tasks for 3D graphs?

Methods

- Overview

- Node-level : Equivariant Force Prediction (EFP)
- Graph-level : Invariant Noise-scale Prediction (INP)



Methods

- Energy-based Molecular Modeling
- 3D graph : atom representations H + inter-atomic connections \mathcal{E} + 3D positions \mathbf{X}
- Obtain the node-level representation from the EGN model

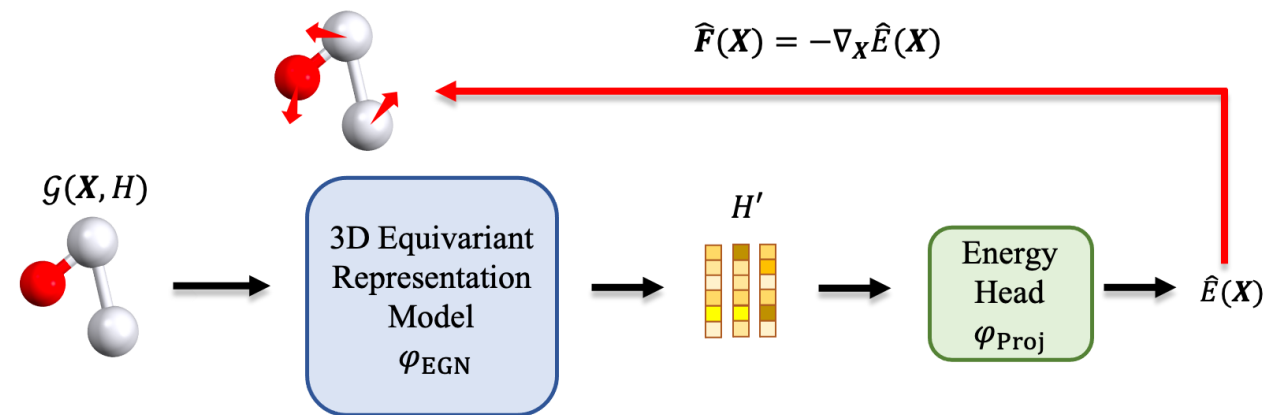
$$H' = \varphi_{\text{EGN}}(\mathbf{X}, H, \mathcal{E})$$

- Predict the graph-level energy via a pooling operation

$$\hat{E}(\mathbf{X}) = \varphi_{\text{proj}}\left(\sum_{i=1}^N h'_i\right)$$

- Forces decrease the potential energy

$$\hat{\mathbf{F}}(\mathbf{X}) = -\nabla_{\mathbf{X}} \hat{E}(\mathbf{X})$$



Methods

- How to fit the predicted forces with reasonable “labels”?
- Assume the training conformers obey a Boltzmann energy distribution

$$p(\mathbf{X}) = \frac{1}{Z} \exp\left(-\frac{E(\mathbf{X})}{kT}\right)$$

- Forces are the negative gradients of the energy E over the coordinates \mathbf{X}

$$\nabla_{\mathbf{X}} \log p(\mathbf{X}) \propto -\nabla_{\mathbf{X}} E(\mathbf{X}) := \mathbf{F}.$$

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Force “labels” !

$$\mathcal{L}_{\text{EFP}} = \mathbb{E}_{\mathcal{G} \sim \mathbb{G}} [\|\hat{\mathbf{F}}(\mathbf{X}) - \nabla_{\mathbf{X}} \log p(\mathbf{X})\|_F^2]$$

Methods

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- Forces are the negative gradients of the energy E over the coordinates \mathbf{X}

$$\nabla_{\mathbf{X}} \log p(\mathbf{X}) \propto -\nabla_{\mathbf{X}} E(\mathbf{X}) := \mathbf{F}.$$

Force “labels” !

- Denoise score matching

$$\mathcal{L}_{\text{EFP-DN}} = \mathbb{E}_{\mathcal{G} \sim \mathbb{G}, \tilde{\mathbf{X}} \sim p(\tilde{\mathbf{X}} | \mathbf{X})} [\|\hat{\mathbf{F}}(\tilde{\mathbf{X}}) - \nabla_{\tilde{\mathbf{X}}} \log p(\tilde{\mathbf{X}} | \mathbf{X})\|_F^2]$$

Methods

- Doubly E(3)-invariance

$$p(g_1 \cdot \tilde{\mathbf{X}} \mid g_2 \cdot \mathbf{X}) = p(\tilde{\mathbf{X}} \mid \mathbf{X}), \forall g_1, g_2 \in \text{E}(3)$$

- Our proposed Riemann-Gaussian distribution

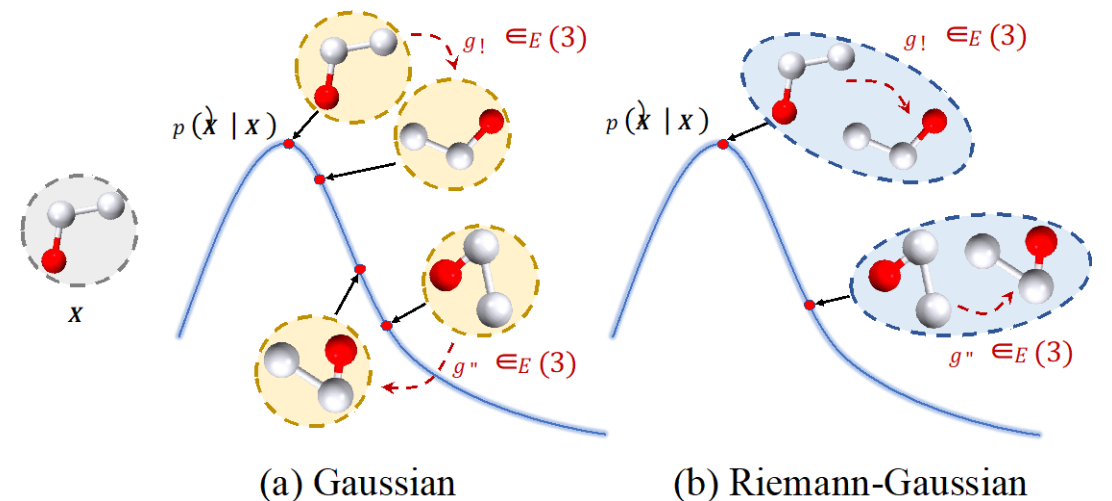
$$p_\sigma(\tilde{\mathbf{X}} \mid \mathbf{X}) = \text{Rie}_\sigma(\tilde{\mathbf{X}} \mid \mathbf{X}) := \frac{1}{Z(\sigma)} \exp\left(-\frac{d^2(\tilde{\mathbf{X}}, \mathbf{X})}{4\sigma^2}\right)$$

- Let $\mathbf{Y} = \mathbf{X} - \mu(\mathbf{X})$ be the zero-mean positions, the distance kernel is determined on the inner-product matrix to satisfy the doubly E(3)-invariance

$$d(\mathbf{X}_1, \mathbf{X}_2) = \|\mathbf{Y}_1^\top \mathbf{Y}_1 - \mathbf{Y}_2^\top \mathbf{Y}_2\|_F$$

- Targeted gradients

$$\nabla_{\tilde{\mathbf{X}}} \log p_\sigma(\tilde{\mathbf{X}} \mid \mathbf{X}) = -\frac{1}{\sigma^2} [(\tilde{\mathbf{Y}}\tilde{\mathbf{Y}}^\top)\tilde{\mathbf{Y}} - (\tilde{\mathbf{Y}}\mathbf{Y}^\top)\mathbf{Y}]$$

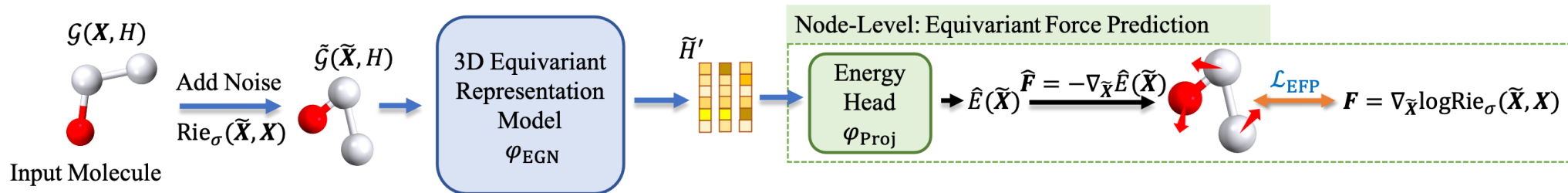


Methods

- Final Equivariant Force Prediction loss

$$\mathcal{L}_{\text{EFP-Final}} = \mathbb{E}_{\mathcal{G} \sim \mathbb{G}, l \sim U(1, L), \tilde{\mathbf{X}} \sim p_{\sigma_l}(\tilde{\mathbf{X}} | \mathbf{X})}$$
$$\left[\sigma_l^2 \left\| \frac{1}{\sigma_l} \hat{\mathbf{F}}(\tilde{\mathbf{X}}) - \frac{1}{\alpha} \nabla_{\tilde{\mathbf{X}}} \log p_{\sigma_l}(\tilde{\mathbf{X}} | \mathbf{X}) \right\|_F^2 \right]$$

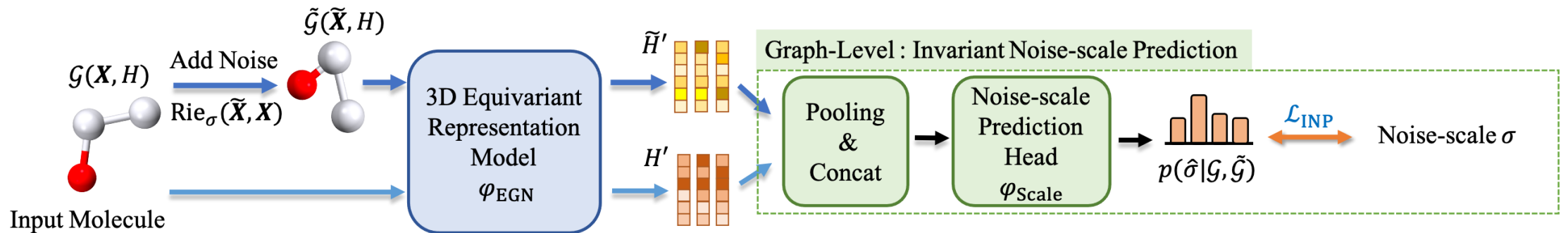
- $\alpha = (\|\tilde{\mathbf{Y}}\tilde{\mathbf{Y}}^\top\|_F + \|\tilde{\mathbf{Y}}\mathbf{Y}^\top\|_F)/2$ for numerical stability



Methods

- Graph-level Invariant Noise-scale Prediction
- Discriminate the noise-scale given the original and perturbed graph
- Let H' , \tilde{H}' be the output node representation of the original and perturbed graph
- The predicted probability is $\mathbf{p} \in \mathbb{R}^L = \varphi_{Scale}(\sum_{i=1}^N h'_i, \sum_{i=1}^N \tilde{h}'_i)$
- INP loss

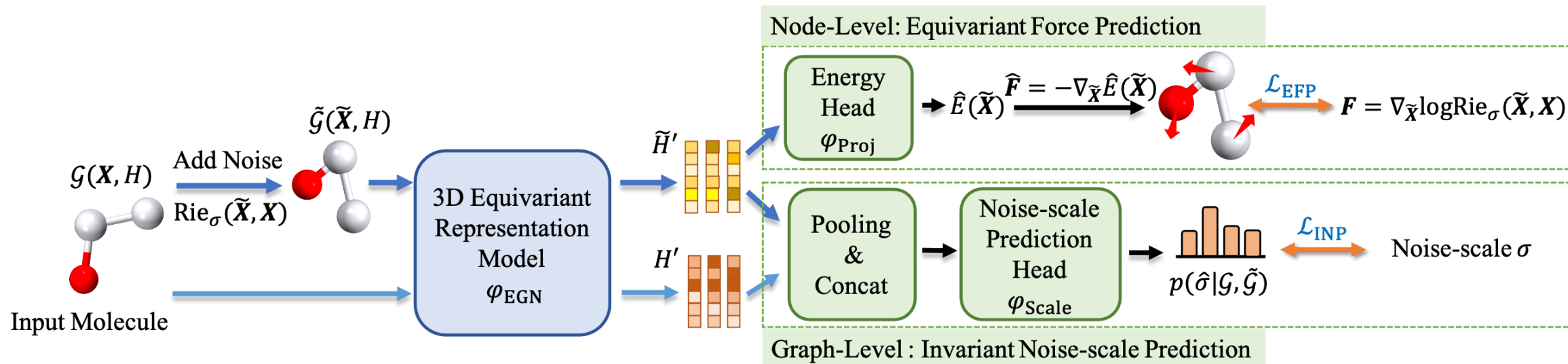
$$\mathcal{L}_{INP} = \mathbb{E}_{\mathcal{G} \sim \mathbb{G}, l \sim U(1, L), \tilde{\mathbf{X}} \sim p_{\sigma_l}(\tilde{\mathbf{X}} | \mathbf{X})} [\mathcal{L}_{CE}(\mathbb{I}[l], \mathbf{p})]$$



Methods

- Combination of the two tasks

$$\mathcal{L} = \lambda_1 \mathcal{L}_{\text{EFP-Final}} + \lambda_2 \mathcal{L}_{\text{INP}}$$



Experiments

- Datasets
- Pretraining
 - 100,000 conformations from GEOM
 - Filter molecules in downstream task
- Downstream tasks
 - QM9, 100k/18k/13k for training/validation/testing
 - MD17, 9500/500/others for training/validation/testing
- Backbone model
 - EGNN (main), SchNet, TorchMD-Net (analysis)
- Baselines
 - 2D pretraining
 - Contrastive : InfoGraph, GCC, GraphCL, JOAO, JOAOv2
 - Generative : AttrMask, EdgePred, GPT-GNN
 - 2D + 3D pretraining
 - GraphMVP, 3D Infomax
 - 3D pretraining
 - ChemRL-GEM, PosPred

Experiments

Force	Aspirin	Benzene	Ethanol	Malon.	Naph.	Salicylic	Toluene	Uracil	Average
Base (Satorras, Hoogeboom, and Welling 2021)	0.3885	0.1861	0.0599	0.1464	0.3310	0.2683	0.1563	0.1323	0.2086
AttrMask (Hu et al. 2020a)	0.3643	0.2277	0.0567	0.1456	0.1773	0.3890	0.1093	0.1560	0.2032
EdgePred (Hamilton, Ying, and Leskovec 2017)	0.4707	0.2036	0.0743	0.1268	0.2310	0.3400	0.1854	0.1933	0.2281
GPT-GNN (Hu et al. 2020b)	0.4278	0.2492	0.0703	0.1484	0.2080	0.3609	0.1541	0.2219	0.2301
InfoGraph (Sun et al. 2020)	0.6578	0.2743	0.1257	0.2647	0.2860	0.5793	0.3821	0.4238	0.3742
GCC (Qiu et al. 2020)	0.3996	0.2346	0.0662	0.1484	0.2798	0.4263	0.3378	0.2369	0.2662
GraphCL (You et al. 2020)	<u>0.2333</u>	<u>0.1845</u>	<u>0.0503</u>	0.0852	<u>0.0966</u>	<u>0.1587</u>	<u>0.0725</u>	<u>0.1167</u>	<u>0.1247</u>
JOAO (You et al. 2021b)	<u>0.3646</u>	0.2331	0.0642	0.1029	0.2017	0.3020	0.1322	0.1683	0.1961
JOAOv2 (You et al. 2021b)	0.3447	0.2198	0.0568	0.0981	0.1889	0.2753	0.1001	0.1850	0.1836
GraphMVP (Liu et al. 2021)	0.3198	0.2800	0.0629	<u>0.0788</u>	0.2350	0.2641	0.0903	0.1339	0.1831
3D Infomax (Stärk et al. 2022)	0.4592	0.1914	0.0705	0.1263	0.2642	0.3401	0.2032	0.1836	0.2298
GEM (Fang et al. 2022)	0.3994	0.2105	0.0871	0.1161	0.1489	0.2344	0.1193	0.1827	0.1873
PosPred	0.3050	0.2023	0.0519	0.0937	0.0971	0.2481	0.0945	0.1270	0.1525
3D-EMGP	0.1560	0.1648	0.0389	0.0737	0.0829	0.1187	0.0619	0.0773	0.0968

Table 1: MAE (lower is better) on MD17 force prediction. All methods share the same backbone as Base.

	α	Δ_ϵ	ϵ_{HOMO}	ϵ_{LUMO}	μ	C_ν	G	H	R^2	U	U_0	ZPVE
Base (Satorras, Hoogeboom, and Welling 2021)	0.070	49.9	28.0	24.3	0.031	0.031	<u>10.1</u>	10.9	0.067	9.7	<u>9.3</u>	1.51
AttrMask (Hu et al. 2020a)	0.072	50.0	31.3	37.8	0.020	0.062	11.2	11.4	0.423	10.8	10.7	1.90
EdgePred (Hamilton, Ying, and Leskovec 2017)	0.086	58.2	37.4	31.9	0.039	0.038	14.5	14.8	0.112	14.2	14.7	1.81
GPT-GNN (Hu et al. 2020b)	0.103	54.1	35.7	28.8	0.039	0.032	12.2	14.8	0.158	24.8	12.0	1.75
InfoGraph (Sun et al. 2020)	0.099	72.2	48.1	38.1	0.041	0.030	16.5	14.5	0.114	14.9	16.4	1.69
GCC (Qiu et al. 2020)	0.085	57.7	37.7	32.3	0.041	0.034	12.8	14.5	0.104	13.2	13.1	1.66
GraphCL (You et al. 2020)	<u>0.066</u>	45.5	26.8	22.9	0.027	<u>0.028</u>	10.2	9.6	0.095	<u>9.7</u>	9.6	<u>1.42</u>
JOAO (You et al. 2021b)	0.068	46.0	28.2	22.8	0.028	0.030	10.5	10.0	0.076	9.9	10.1	1.48
JOAOv2 (You et al. 2021b)	<u>0.066</u>	45.0	27.8	22.2	0.027	<u>0.028</u>	9.9	<u>9.2</u>	0.087	9.8	9.5	1.43
GraphMVP (Liu et al. 2021)	0.070	46.9	28.5	26.3	0.031	0.033	11.2	10.4	0.082	10.3	10.2	1.63
3D Infomax (Stärk et al. 2022)	0.075	48.8	29.8	25.7	0.034	0.033	13.0	12.4	0.122	12.5	12.7	1.67
GEM (Fang et al. 2022)	0.081	52.1	33.8	27.7	0.034	0.035	13.2	13.3	0.089	12.6	13.4	1.73
PosPred	0.067	<u>40.6</u>	<u>25.1</u>	<u>20.9</u>	0.024	0.035	10.9	10.2	0.115	10.3	10.2	1.46
3D-EMGP	0.057	37.1	21.3	18.2	0.020	0.026	9.3	8.7	0.092	8.6	8.6	1.38

Table 2: MAE (lower is better) on QM9. All methods share the same backbone as Base.

Experiments

- Ablation studies on each components

	Proposed Components				Average MAE	
	EFP	INP	Riemann	Energy	Energy	Force
Base					0.1191	0.2086
Ours	✓	✓	✓	✓	0.0876	0.0968
INP only		✓	✓	✓	0.0974	0.1350
EFP only	✓		✓	✓	0.0905	0.1193
Gaussian	✓	✓		✓	0.0912	0.1060
Distance	✓ ¹	✓			0.0931	0.1292
Direct	✓	✓	✓		0.0914	0.1267

Table 3: Ablation studies on MD17. ¹Denoising on distance.

- Generalization on different backbones

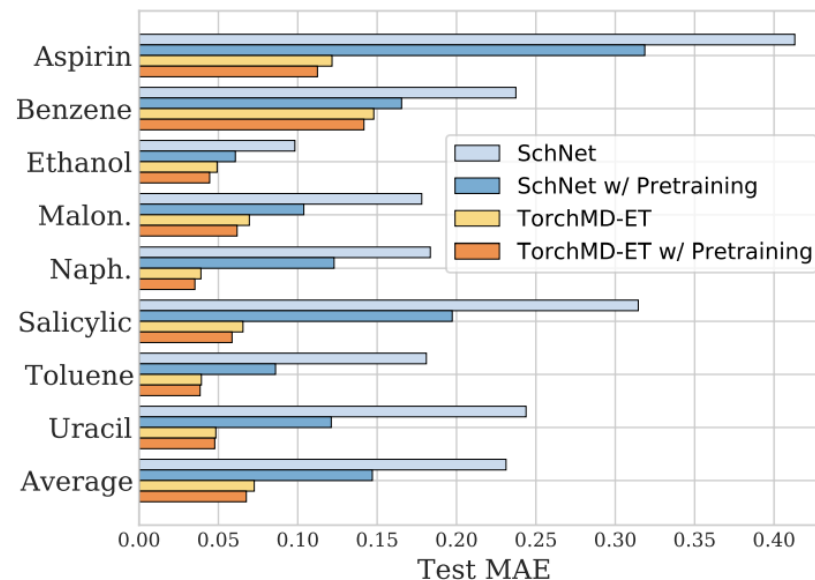


Figure 3: MAE on MD17 with different backbones.

Experiments

- **Energy landscape visualization**

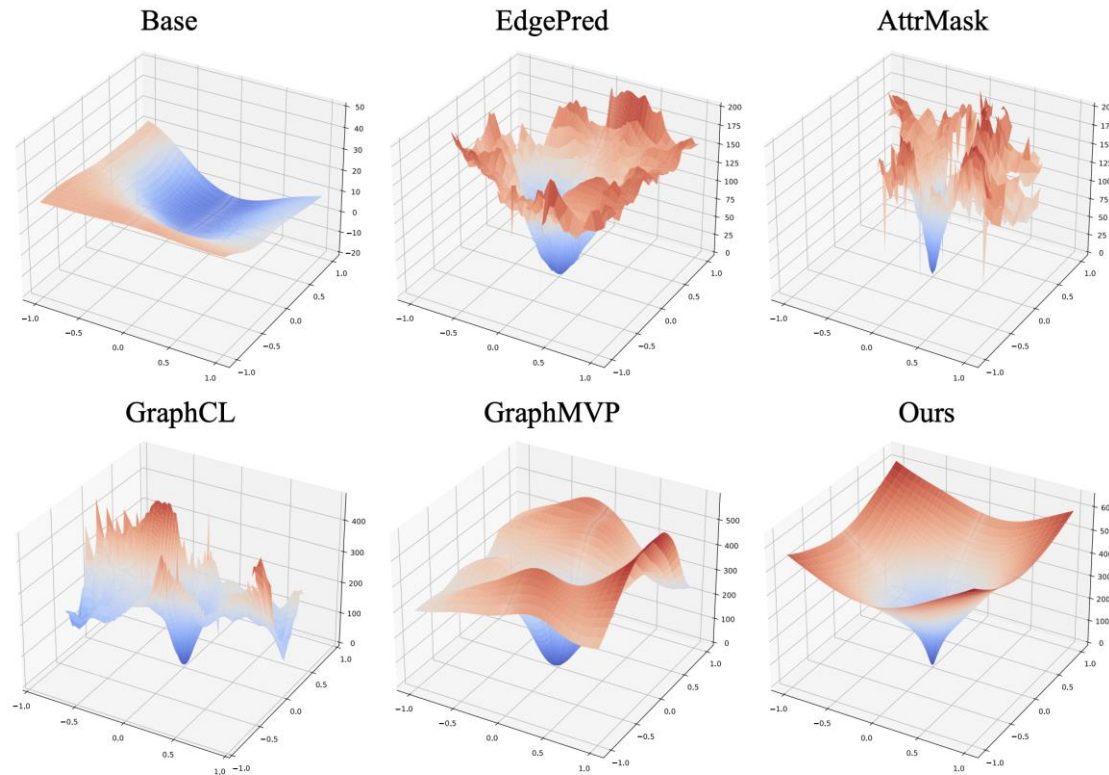


Figure 4: Energy landscape of different pretrained models.

Conclusion

- We propose a general 3D pretraining framework
 - Node-level equivariant force prediction via energy-based modeling and Riemann-Gaussian distribution
 - Graph-level invariant noise-scale prediction as a surrogate task
- We conduct experiments on QM9 and MD17, showcasing the superiority of our method
- We provide necessary analyses and visualizations to verify and explain the effectiveness of our method

Thanks!